# nag\_anova\_random (g04bbc)

## 1. Purpose

**nag\_anova\_random (g04bbc)** computes the analysis of variance and treatment means and standard errors for a randomized block or completely randomized design.

## 2. Specification

#include <nag.h>
#include <nagg04.h>

## 3. Description

In a completely randomized design the experimental material is divided into a number of units, or plots, to which a treatment can be applied. In a randomized block design the units are grouped into blocks so that the variation within blocks is less than the variation between blocks. If every treatment is applied to one plot in each block it is a complete block design. If there are fewer plots per block than treatments then the design will be an incomplete block design and may be balanced or partially balanced.

For a completely randomized design, with t treatments and  $\boldsymbol{n}_t$  plots per treatment, the linear model is

$$y_{ij} = \mu + \tau_j + e_{ij}, \quad j = 1, 2..., t; \ i = 1, 2..., n_j,$$

where  $y_{ij}$  is the *i*th observation for the *j*th treatment,  $\mu$  is the overall mean,  $\tau_j$  is the effect of the *j*th treatment and  $e_{ij}$  is the random error term. For a randomised block design, with *t* treatments and *b* blocks of *k* plots, the linear model is

$$y_{ij(l)} = \mu + \beta_i + \tau_l + e_{ij}, \quad i = 1, 2..., b; \ j = 1, 2..., k; \ l = 1, 2, ..., t,$$

where  $\beta_i$  is the effect of the *i*th block and the ij(l) notation indicates that the *l*th treatment is applied to the *i*th plot in the *j*th block.

The completely randomized design gives rise to a one-way analysis of variance. The treatments do not have to be equally replicated, i.e., do not have to occur the same number of times. First the overall mean,  $\hat{\mu}$ , is computed and subtracted from the observations to give  $y'_{ij} = y_{ij} - \hat{\mu}$ . The estimated treatment effects,  $\hat{\tau}_j$  are then computed as the treatment means of the mean adjusted observations,  $y'_{ij}$ , and the treatment sum of squares can be computed from the sum of squares of the treatment totals of the  $y'_{ij}$  divided by the number of observations per treatment total,  $n_j$ . The final residuals are computed as  $r_{ij} = y'_{ij} - \hat{\tau}_j$ , and, from the residuals, the residual sum of squares is calculated.

For the randomised block design the mean is computed and subtracted from the observations to give  $y'_{ij(l)} = y_{ij(l)} - \hat{\mu}$ . The estimated block effects, ignoring treatment effects,  $\hat{\beta}_i$ , are then computed using the block means of the  $y'_{ij(l)}$  and the unadjusted sum of squares computed as the sum of squared block totals for the  $y'_{ij(l)}$  divided by number of plots per block, k. The block adjusted observations are then computed as  $y''_{ij(l)} = y'_{ij(l)} = \hat{\beta}_i$ . In the case of the complete block design, with the same replication for each treatment within each block, the blocks and treatments are orthogonal, and so the treatment effects are estimated as the treatment means of the block adjusted observations,  $y''_{ij(l)}$ . The treatment sum of squares is computed as the sum of squared treatment totals of the  $y'_{ij(l)}$  divided by the number of replicates to the treatments, r = bk/t. Finally the residuals, and hence the residual sum of squares, are given by  $r_{ij(l)} = y'_{ij(l)} - \hat{\tau}_l$ .

For a design without the same replication for each treatment within each block the treatments and the blocks will not be orthogonal, so the treatments adjusted for blocks need to be computed. The adjusted treatment effects are found as the solution to the equations

$$(R - NN^T / k)\hat{\tau} = q$$

where q is the vector of the treatment totals for block adjusted observations,  $y''_{ij(l)}$ , R is a diagonal matrix with  $R_{ll}$  equal to the number of times the *l*th treatment is replicated, and N is the *t* by *b* incidence matrix, with  $N_{lj}$  equal to the number of times treatment *l* occurs in block *j*. The solution to the equations can be written as

$$\hat{\tau} = \Omega q$$

where  $\Omega$  is a generalized inverse of  $(R - NN^T/k)$ . The solution is found from the eigenvalue decomposition of  $(R - NN^T/k)$ . The residuals are first calculated by subtracting the estimated treatment effects from the block adjusted observations to give  $r'_{ij(l)} = y''_{ij(l)} - \hat{\tau}_l$ . However, since only the unadjusted block effects have been removed and blocks and treatments are not orthogonal, the block means of the  $r'_{ij(l)}$  have to be subtracted to give the correct residuals,  $r_{ij(l)}$  and residual sum of squares.

The mean squares are computed as the sum of squares divided by the degrees of freedom. The degrees of freedom for the unadjusted blocks is b - 1, for the completely randomised and the complete block designs the degrees of freedom for the treatments is t - 1. In the general case the degrees of freedom for treatments is the rank of the matrix  $\Omega$ . The *F*-statistic given by the ratio of the treatment mean square to the residual mean square tests the hypothesis

$$H_0: \tau_1 = \tau_2 = \ldots = \tau_t = 0.$$

The standard errors for the difference in treatment effects, or treatment means, for the completely randomized or the complete block designs, are given by

se 
$$(\tau_j - \tau_{j*}) = \left(\frac{1}{n_j} + \frac{1}{n_{j*}}\right)s^2$$

where  $s^2$  is the residual mean square and  $n_j = n_{j*} = b$  in the complete block design. In the general case the variances of the treatment effects are given by

 $\operatorname{var}(\tau) = \Omega s^2$ 

from which the appropriate standard errors of the difference between treatment effects or the difference between adjusted means can be calculated.

In the complete block design all the information on the treatment effects is given by the within block analysis. In other designs there may be a loss of information due to the non-orthogonality of treatments and blocks. The efficiency of the within block analysis in these cases is given by the (canonical) efficiency factors, these are the non-zero eigenvalues of the matrix  $(R - NN^T/k)$ , divided by the number of replicates in the case of equal replication, or by the mean of the number of replicates in the unequally replicated case, see John (1987). If more than one eigenvalue is zero then the design is said to be disconnected and some treatments can only be compared using a between block analysis.

## 4. Parameters

 $\mathbf{n}$ 

Input: the number of observations, n.

Constraint:  $n \ge 2$  and if **iblock**  $\ge 2$ , **n** must be a multiple of **iblock**.

y[n]

Input: the observations in the order as described by **blocks** and **nt**.

# blocks

Input: **blocks** indicates the block structure.

If  $blocks = Nag_NoBlocks$  then there are no blocks, i.e., it is a completely randomized design.

If  $blocks = Nag_SerialBlocks$  then the data should be input by blocks, i.e., y must contain the observations for block 1 followed by the observations for block 2, etc.

If **blocks** = **Nag\_ParallelBlocks** then the data is input in parallel with respect to blocks, i.e.,  $\mathbf{y}[0]$  must contain the first observation for block 1,  $\mathbf{y}[1]$  must contain the first observation for block 2...  $\mathbf{y}[\mathbf{iblock}-1]$  must contain the first observation for block  $\mathbf{iblock}$ ,  $\mathbf{y}[\mathbf{iblock}]$  must contain the second observation for block 1, etc.

Constraint: blocks = Nag\_NoBlocks, Nag\_SerialBlocks or Nag\_ParallelBlocks.

## iblock

Input: **iblock** indicates the number of blocks, b.

Constraint: if  $blocks = Nag\_SerialBlocks$  or  $blocks = Nag\_ParallelBlocks$  then  $iblock \ge 2$ ; it is not referenced otherwise.

## $\mathbf{nt}$

Input: the number of treatments, t. If only blocks are required in the analysis then set  $\mathbf{nt} = 1$ .

Constraint: if **iblock**  $\geq 2$ , **nt**  $\geq 1$ , otherwise **nt**  $\geq 2$ .

## it[dim1]

Note: the dimension, dim1 of the array it must be at least **n** if  $\mathbf{nt} \ge 2$ , and 1 otherwise. Input:  $\mathbf{it}[i-1]$  indicates which of the **nt** treatments plot *i* received, for  $i = 1, 2, ..., \mathbf{n}$ . If  $\mathbf{nt} = 1$ , it is not referenced.

Constraint:  $1 \leq \mathbf{it}[i-1] \leq \mathbf{nt}$ , for  $i = 1, 2, \dots, \mathbf{n}$ .

## gmean

Output: the grand mean,  $\hat{\mu}$ .

## bmean[dim1]

Note: the dimension, dim1 of the array **bmean** must be at least max(1,**iblock**). Output: if **blocks** = **Nag\_SerialBlocks** or **Nag\_ParallelBlocks**, **bmean**[j-1] contains the mean for the *j*th block,  $\hat{\beta}_j$  for j = 1, 2, ..., b. It is not referenced otherwise.

## tmean[nt]

Output: if  $\mathbf{nt} \geq 2$ ,  $\mathbf{tmean}[l-1]$  contains the (adjusted) mean for the *l*th treatment,  $\hat{\mu}^* + \hat{\tau}_l$ , for  $l = 1, 2, \ldots, t$ , where  $\hat{\mu}^*$  is the mean of the treatment adjusted observations,  $y_{ij(l)} - \hat{\tau}_l$ .

## table[4][5]

Output: the analysis of variance table. Column 1 contains the degrees of freedom, column 2 the sum of squares, and where appropriate, column 3 the mean squares, column 4 the F-statistic and column 5 the significance level of the F-statistic. Row 1 is for Blocks, row 2 for Treatments, row 3 for Residual and row 4 for Total. Mean squares are computed for all but the Total row; F-statistics and significance are computed for Treatments and Blocks, if present. Any unfilled cells are set to zero.

## c[nt][tdc]

Output: if  $\mathbf{nt} \geq 2$ , the upper triangular part of  $\mathbf{c}$  contains the variance-covariance matrix of the treatment effects, the strictly lower triangular part contains the standard errors of the difference between two treatment effects (means), i.e.,  $\mathbf{c}[i-1][j-1]$  contains the covariance of treatment *i* and *j* if  $j \geq i$  and the standard error of the difference between treatment *i* and *j* if j < i for  $i = 1, 2, \ldots, t; j = 1, 2, \ldots, t$ .

## $\mathbf{tdc}$

Input: The second dimension of the array c as declared in the calling program. Constraint:  $tdc \geq nt$ .

# irep[nt]

Output: if  $\mathbf{nt} \geq 2$ , the treatment replications,  $R_{ll}$ , for  $l = 1, 2, \dots, \mathbf{nt}$ .

## r[n]

Output: the residuals,  $r_i$ , for  $i = 1, 2, \ldots, \mathbf{n}$ .

## ef[nt]

Output: if  $\mathbf{nt} \geq 2$ , the canonical efficiency factors.

## tol

Input: the tolerance value used to check for zero eigenvalues of the matrix  $\Omega$ . If  $\mathbf{tol} = 0.0$  a default value of  $10^{-5}$  is used.

Constraint:  $tol \ge 0.0$ .

## irdf

Input: an adjustment to the degrees of freedom for the residual and total. If  $irdf \ge 1$  the degrees of freedom for the total is set to  $\mathbf{n} - irdf$  and the residual degrees of freedom adjusted accordingly. If irdf = 0, the total degrees of freedom for the total is set to  $\mathbf{n} - 1$ , as usual. Constraint:  $irdf \ge 0$ .

## fail

The NAG error parameter, see the Essential Introduction to the NAG C Library.

## 5. Error Indications and Warnings

## NE\_BAD\_PARAM

On entry, parameter **blocks** had an illegal value.

#### NE\_INT\_ARG\_LT

On entry, **n** must not be less than 2:  $\mathbf{n} = \langle value \rangle$ . On entry, **nt** must not be less than 1:  $\mathbf{nt} = \langle value \rangle$ . On entry, **irdf** must not be less than 0: **irdf** =  $\langle value \rangle$ .

# NE\_REAL\_ARG\_LT

On entry, tol must not be less than 0.0: tol =  $\langle value \rangle$ .

# NE\_INT

On entry,  $iblock = \langle value \rangle$ . Constraint:  $iblock \geq 2$  when  $blocks = Nag_NoBlocks$ . On entry,  $nt = \langle value \rangle$ . Constraint:  $nt \geq 2$  when  $blocks = Nag_NoBlocks$ .

## NE\_2\_INT\_ARG\_LT

On entry,  $\mathbf{tdc} = \langle value \rangle$  while  $\mathbf{nt} = \langle value \rangle$ . These parameters must satisfy  $\mathbf{tdc} \geq \mathbf{nt}$ .

## NE\_INT\_2

On entry,  $\mathbf{n} = \langle value \rangle$ ,  $\mathbf{iblock} = \langle value \rangle$ . Constraint: when  $\mathbf{iblock} \geq 2$ ,  $\mathbf{n}$  must be a multiple of  $\mathbf{iblock}$ .

## NE\_INTARR

On entry,  $\mathbf{it}[\langle value \rangle] = \langle value \rangle$ . Constraint:  $1 \leq \mathbf{it}[i-1] \leq \mathbf{nt}$ , for  $i = 1, 2, ..., \mathbf{n}$ .

## NE\_IT\_ARRAY

No value of  $\mathbf{it}[j-1] = j$  for some  $j = 1, 2, \dots, \mathbf{nt}$ .

# NE\_ARRAY\_CONSTANT

On entry, the elements of the array  $\mathbf{y}$  are constant.

## NE\_G04BB\_STDERR

A computed standard error is zero due to rounding errors.

This is an unlikely error exit.

# NE\_G04BB\_DESIGN

The design is disconnected; the standard errors may not be valid. The design may be nested.

## NE\_G04BB\_TREAT

The treatments are totally confounded with blocks, so the treatment sum of squares and degrees of freedom are zero. The analysis of variance table is not computed, except for block and total sums of squares and degrees of freedom.

# NE\_G04BB\_CONV

The eigenvalue computation has failed to converge.

This is an unlikely error exit.

# NE\_G04BB\_RES\_DF

The residual degrees of freedom or the residual sum of squares are zero, columns 3, 4 and 5 of the analysis of variance table will not be computed and the matrix of standard errors and covariances, C, will not be scaled by s or the square of s.

# NE\_ALLOC\_FAIL

Memory allocation failed.

# 6. Further Comments

To estimate missing values the Healy and Westmacott procedure or its derivatives may be used, see John and Quenouille (1977). This is an iterative procedure in which estimates of the missing values are adjusted by subtracting the corresponding values of the residuals. The new estimates are then used in the analysis of variance. This process is repeated until convergence. A suitable initial value may be the grand mean  $\hat{\mu}$ . When using this procedure **irdf** should be set to the number of missing values plus one to obtain the correct degrees of freedom for the residual sum of squares.

For designs such as Latin squares one more of the blocking factors has to be removed in a preliminary analysis before the final analysis using extra calls to nag\_anova\_random. The residuals from the preliminary analysis are then input to nag\_anova\_random. In these cases **irdf** should be set to the difference between **n** and the residual degrees of freedom from preliminary analysis. Care should be taken when using this approach as there is no check on the orthogonality of the two analyses.

For analysis of covariance the residuals are obtained from an analysis of variance of both the response variable and the covariates. The residuals from the response variable are then regressed on the residuals from the covariates using, say, nag\_regress\_confid\_interval (g02cbc) or nag\_regsn\_mult\_linear (g02dac). The results from those routines can be used to test for the significance of the covariates. To test the significance of the treatment effects after fitting the covariate, the residual sum of squares from the regression should be compared with the residual sum of squares obtained from the equivalent regression but using the residuals from fitting blocks only.

## 6.1. Accuracy

The algorithm used by this routine, described in Section 3, achieves greater accuracy than the traditional algorithms based on the subtraction of sums of squares.

## 6.2. References

Cochran W G and Cox G M (1957) Experimental Designs Wiley. Davis O L (ed.)(1978) The Design and Analysis of Industrial Experiments Longman. John J A (1987) Cyclic Designs Chapman and Hall. John J A and Quenouille M H (1977) Experiments: Design and Analysis Griffin. Searle S R (1971) Linear Models Wiley.

# 7. See Also

nag\_regress\_confid\_interval (g02cbc) nag\_regsn\_mult\_linear (g02dac)

# 8. Example

The data, given by John and Quenouille (1977), is for a balanced incomplete block design with 10 blocks and 6 treatments and with 3 plots per block. The observations are the degree of pain experienced and the treatments are penicillin of different potency. The data is input and the analysis of variance table and treatment means are printed.

# 8.1. Program Text

```
/* nag_anova_random}(g04bbc) Example Program.
 * Copyright 1998 Numerical Algorithms Group.
 *
 * Mark 5, 1998.
 */
#include <nag.h>
#include <nag_stdlib.h>
#include <stdio.h>
#include <nagg04.h>
#define NMAX 30
#define NTMAX 6
#define NBMAX 10
#define TMAX 4
#define TDT TMAX
#define TDC NTMAX
main()
  double bmean[NBMAX], c[NTMAX][NTMAX], ef[NTMAX], r[NMAX],
  table[4][5], tmean[NTMAX],y[NMAX];
  double gmean;
  double tol;
  Integer irep[NTMAX], it[NMAX];
  Integer irdf;
  Integer i, j, n;
  Integer ifail;
  Integer nt, nblock;
  Integer tdc = TDC;
  Vprintf("g04bbc Example Program Results\n");
  /* Skip heading in data file */
Vscanf("%*[^\n] ");
  Vscanf("%ld%ld%ld%*[^\n] ",&n, &nt, &nblock);
  if (n <= NMAX)
    {
      for (i = 0; i < n; ++i)
    Vscanf("%lf",&y[i]);</pre>
      Vscanf("%*[^\n]");
      for (i = 0; i < n; ++i)
    Vscanf("%ld",&it[i]);</pre>
      Vscanf("%*[^\n]");
      tol = 5e-6;
      irdf = 0;
      g04bbc(n, y, Nag_SerialBlocks, nblock, nt, it, &gmean, bmean, tmean,
               (double *)table, (double *)c, tdc, irep, r, ef, tol, irdf,
              NAGERR_DEFAULT);
      Vprintf("\nANOVA table\n\n");
Vprintf(" Source df
                                         SS
                                                             MS
                                                                           F\
           Prob\n\n");
```

```
Vprintf(" Blocks ");
for (j = 0; j < 5; ++j)
Vprintf("%10.4f ",table[0][j]);
     Vprintf("\n");
     Vprintf(" Treatments ");
     for (j = 0; j < 5; ++j)
    Vprintf("%10.4f ",table[1][j]);</pre>
     Vprintf("\n");
     Vprintf(" Residual ");
for (j = 0; j < 3; ++j)
Vprintf("%10.4f ",table[2][j]);
     Vprintf("\n");
                              ");
     Vprintf(" Total
     for (j = 1; j <= 2; ++j)
Vprintf("%10.4f ",table[3][j-1]);</pre>
     Vprintf("\n");
     Vprintf("\nEfficiency Factors\n\n");
     for (i = 0; i < nt; ++i)
    Vprintf("%10.5f",ef[i]);</pre>
     Vprintf("\n");
     Vprintf("\n%s%10.5f\n"," Grand Mean",gmean);
     Vprintf("\nTreatment Means\n\n");
     for (i = 1; i <= nt; ++i)
    Vprintf("%10.5f",tmean[i-1]);</pre>
     Vprintf("\n");
     Vprintf("\nStandard errors of differences between means\n\n");
     for (i = 1; i < nt; ++i)
        {
          for (j = 0; j < i; ++j)
    Vprintf("%10.5f",c[i][j]);</pre>
           Vprintf("\n");
        }
  }
else
  {
     Vprintf( "Incorrect input value of n.\n");
     exit(EXIT_FAILURE);
  }
exit(EXIT_SUCCESS);
```

## 8.2. Program Data

}

g04bbc Example Program Data 30 6 10 : n, nt, iblock 154 5 10 6 293 486 247 675 572 724 842 10 8 7 : у 123 1 2 4 1 3 5 146 156 236 245 256

	3 4 5 3 4 6		: i	t				
8.3.	Program Resu	Program Results						
	g04bbc Example Program Results							
	ANOVA table							
	Source	df	SS	M	S	F	Prob	
	Blocks Treatments Residual Total	9.000 5.000 15.000 29.000	00       60.         00       101.         00       20.         00       182.	0000 7778 2 8889 6667	6.6667 0.3556 1.3926	4.7872 14.6170	0.0039 0.0000	
	Efficiency F	actors						
	0.00000	0.80000	0.80000	0.80000	0.80000	0.80000		
	Grand Mean 5.33333							
	Treatment Means							
	2.50000	7.25000	8.08333	5.91667	2.91667	5.33333		
	Standard errors of differences between means							
	0.83444 0.83444 0.83444 0.83444 0.83444	0.83444 0.83444 0.83444 0.83444	0.83444 0.83444 0.83444	0.83444 0.83444	0.83444			